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[PDF] MULTI-**SENSOR** ORDNANCE DETECTION AND MAPPING
SYSTEM Michael Kerr ...
File Format: PDF/Adobe Acrobat - View as HTML
... Detection Abstract The Air **Force** Research Laboratory ... for video **feedback**,
the **joystick**
control box ... reviewing diagnostic information, and viewing video **feedback**. ...
https://www.denix.osd.mil/denix/Public/News/
OSD/UXO/Conferences/Forum99/DT_Kerr.pdf - Similar pages

[PS] International Conference on Intelligent Robots and Systems
[IROS ...
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... rate, structural resonance frequencies, **sensor** noise, amplifier ... were chosen
to **filter**
frequencies above ... of-freedom **force-feedback joystick** for telemanipulation ...
www.cs.cmu.edu/afs/cs/project/msl/ www/publications/iros95.maglev.ps - Similar
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TELEMANIPULATION USING A VIRTUAL ...
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... to the use of other devices, such as **joystick** type [2 ... from their conclusions of
the
feedback data is ... **Force** replication to the human operator: The development
of ...
www.iser02.unisa.it/papers/37.pdf - Similar pages

[PS] Direct Manipulation in Virtual Reality Steve Bryson
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... of real-world objects -keyboard, **joystick**, treadmill, bicycle ... e^very difficult to
predictively **filter** hand motion ... without high-resolution **force feedback**?-if not ...
people.nas.nasa.gov/~bryson/courses/manipulate.ps - Similar pages

Switches
... for mounting on a wheelchair tray next to the **joystick** control ... This thin membrane
switch requires very little **force** or movement to activate ... No auditory **feedback**. ...
www.ndipat.org/loanlib/switch.htm - 21k - Cached - Similar pages

Integration of Visual and Haptic **Feedback** for Teleoperation (...
... of Visual and Haptic **Feedback** for Teleoperation ... 1964 1 Stabilizing impacts in **force**
reflecting teleoperation ... for a 6 dof telerobotic **joystick** (context) - Fischer ...

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... **Joystick** control of the stage (implemented in our laboratory using LabVIEW ... this speed
is sufficient to implement **force** or position **feedback** control using ...
www.stanford.edu/group/blocklab/ Lang%20et%20al%20BJ%202002.pdf - Similar pages

[PDF] A Steady-Hand Robotic System for Microsurgical Augmentation
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... either passive, such as a trackball, **joystick** or stylus ... for selected joints; q: joint
position **feedback** from encoders ... This bias **force** is stored in the robot base ...
www.cs.jhu.edu/~rht/Papers/Miccai99/ SteadyHandFinal.pdf - Similar pages

SIGGRAPH Computer Graphics Newsletter - Interaction in 3D ...
... 8 shows some examples of 6 DOF "**joystick**" devices that ... integration) is a low
pass **filter**, reducing high ... can also be equipped with **force feedback**, as with ...
www.siggraph.org/publications/newsletter/ v32n4/contributions/zhai.html - 31k - Cached - Similar pages

Cyberwizards Group P/L Retail Price List
... Floppy bay adaptors 5.25 to 3.5. $4.80. A4 TECH **JOYSTICK** JST-SF-5. $26.40. ... $278.40.
LogiTech MOMO Racing **Force FeedBack**. $204.00. ... $73.20. LogiTech **Force** 3D. $105.60. ...
https://www.cws.net.au/store/dealerPriceGen/ pricelists/retailhw35575.html - 45k - Cached - Similar pages

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filter P.J. Berkelman and R.L. Ho| **Google Search**

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[details]

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Searched the web for **filter P.J. Berkelman and R.L. Hollis S.E. Salcudean**. Results **1 - 6** of about **7**. Search too

[PS] International Conference on Intelligent Robots and Systems [IROS ...
File Format: Adobe PostScript - View as Text
... **PJ Berkelman** and **RL Hollis SE Salcudean**. ... Digital state estimators were implemented
to **filter** the sensed position data and provide smooth velocity data. ...
www.cs.cmu.edu/afs/cs/project/msl/ www/publications/iros95.maglev.ps - Similar pages

[PDF] Haptic Rendering of Planar Rigid-Body Motion using a Redundant ...
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... further reduced by using the axis-aligned bounding box method to **filter** out pairs ... References
[1] **PJ Berkelman**, **RL Hollis**, and D. Baraff ... [15] **SE Salcudean** and TD ...
www.ece.ubc.ca/~tims/pubs/ICRA2000Constantinescu.pdf - Similar pages

IROS '95 Abstracts
... Environments Using a Magnetic Levitation Haptic Interface **PJ Berkelman**, **RL Hollis**,
and **SE Salcudean**. ... A Kalman **Filter** Based Visual Tracking Algorithm for an ...
www.computer.org/conferen/proceed/IROS95/TOC.HTM - 50k - Cached - Similar pages

[PDF] Stable Haptic Interaction with Virtual Environments
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... **Salcudean** and Vlaar [3] studied the stability properties of ... the imaginary axis (unit
circle), and **Pj** P j ... of an appropriate anti-aliasing **filter** before sampling ...
brl.ee.washington.edu/publications/Rep120.pdf - Similar pages

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... An inter- esting design using a hemispherical device controlled by magnetic fields
has been proposed by **Berkelman** and **Hollis** [5]. Although this device has 6 ...
wwwrobot.gmc.ulaval.ca/~birgle00/Shared/SHaDe2002.pdf - Similar pages

[PS] Modeling Mechanism and Hand Impedances for
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... several degrees of rotation (Buttolo and Hannaford, 1995; **Berkelman** and **Hollis**, 1998;
Salcudean ... measured data was filtered with a double pole **filter** at 5 Hz ...
osl-www.colorado.edu/~toph/publications/Thesis.ps - Similar pages

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the 6 already displayed.
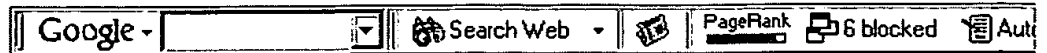If you like, you can repeat the search with the omitted results included.*

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